

$$\vec{S} = (S_x, S_y, S_z)$$

$$\vec{L} = \vec{r} \times \vec{p}$$

$$[S_i, S_j] = i \epsilon_{ijk} S_k$$

$$[L_i, L_j] = i \epsilon_{ijk} L_k$$

$$S^2 |s, m_s\rangle = \hbar^2 s(s+1) |s, m_s\rangle$$

$$S_z |s, m_s\rangle = \hbar m_s |s, m_s\rangle$$

زیر اسپین

$$s = \frac{1}{2}, m_s = \pm \frac{1}{2}$$

$$|\frac{1}{2}, +\frac{1}{2}\rangle = |\uparrow\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\vec{r} \times \vec{p} = \vec{r} \times \frac{\hbar}{i} \vec{\nabla}$$

$$|\frac{1}{2}, -\frac{1}{2}\rangle = |\downarrow\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

زیر اسپین

$$U_{\delta\varphi} = e^{\frac{i}{\hbar} \delta\varphi \cdot \vec{L}}$$

$$\vec{r} \rightarrow \vec{r}' = \vec{r} + \delta\varphi \times \vec{r}$$

$$\langle \vec{x} | \psi \rangle = \psi(\vec{x}) \in \mathcal{L}_2(\mathbb{R}^3)$$

$$\begin{pmatrix} \cos\varphi - \sin\varphi & 0 \\ \sin\varphi & \cos\varphi \\ 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$U_{\delta\varphi} \psi(\vec{x}) = \psi(\vec{x}')$$

$$e^{\frac{i}{\hbar} \delta\varphi \cdot \vec{S}} |\uparrow\rangle = |\uparrow'\rangle$$

$$\begin{pmatrix} e^{i\frac{\delta\varphi}{2}} & 0 \\ 0 & e^{-i\frac{\delta\varphi}{2}} \end{pmatrix}_{2 \times 2} \begin{pmatrix} 1 \\ 0 \end{pmatrix}_{2 \times 1} = \begin{pmatrix} \cdot \\ \cdot \end{pmatrix}_{2 \times 1}$$

$$|s\rangle = \alpha_+ |\uparrow\rangle + \alpha_- |\downarrow\rangle$$

spinor

$$\vec{S} = \frac{\hbar}{2} \vec{\sigma}$$

$$e^{\text{Matrix}} = \sum_{n=0}^{\infty} \frac{1}{n!} (\text{Matrix})^n$$

$$|\psi\rangle = \int d^3x' \psi(\vec{x}') |\vec{x}'\rangle$$

$$\langle \vec{x} | \psi \rangle = \psi(\vec{x})$$

$$\langle \vec{x} | \psi \rangle = \int d^3x' \psi(\vec{x}') \frac{\langle \vec{x} | \vec{x}' \rangle}{\delta(\vec{x} - \vec{x}')} = \psi(\vec{x})$$

$$|\psi\rangle = \int d^3x' \left(\psi_+(\vec{x}') |\vec{x}'\rangle \otimes |\uparrow\rangle + \psi_-(\vec{x}') |\vec{x}'\rangle \otimes |\downarrow\rangle \right)$$

\uparrow
 $\langle \vec{x} | \vec{x}' \rangle = \delta(\vec{x} - \vec{x}')$

$$\langle \vec{x} | \psi \rangle = \psi_+(\vec{x}) |\uparrow\rangle + \psi_-(\vec{x}) |\downarrow\rangle$$

$$= \psi_+(\vec{x}) \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \psi_-(\vec{x}) \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \psi_+(\vec{x}) \\ \psi_-(\vec{x}) \end{pmatrix}$$

$$\langle \uparrow | \langle \vec{x} | \psi \rangle = \psi_+(\vec{x})$$

$$\langle \downarrow | \langle \vec{x} | \psi \rangle = \psi_-(\vec{x})$$

$\delta \vec{\varphi} = \delta \varphi \hat{n}$

البرون و حضور میدان الکترومغناطیس

$$H = \left(\frac{1}{2m_e} (\vec{p} + \frac{e}{c} \vec{A})^2 - e\varphi \right) \otimes \mathbb{1}_{2 \times 2} + \frac{1}{c} \mathcal{L}_2(\mathbb{R}^3) \otimes \left(g \mu_B \frac{\vec{B} \cdot \vec{S}}{\hbar} \right)$$

$\vec{p} = \frac{\hbar}{i} \vec{\nabla}$

$H \psi(\vec{x})$

$\mu_B = \frac{e\hbar}{2mc}$

فردیت زار دینامیس ~ 2

$\alpha = \frac{1}{137}$

$\vec{S} = \frac{\hbar}{2} \vec{\sigma}$

ارزاضاعات بخش ساهلیون منظر انتم

$$i\hbar \partial_t \underbrace{\begin{pmatrix} \psi_+(t) \\ \psi_-(t) \end{pmatrix}}_{|\psi(t)\rangle} = H_{sp.} \underbrace{\begin{pmatrix} \psi_+(t) \\ \psi_-(t) \end{pmatrix}}_{|\psi(t)\rangle}$$

$$= g \mu_B \frac{\vec{B} \cdot \vec{S}}{\hbar}$$

$$= g \mu_B \frac{\hbar}{2} B \sigma_3 = \frac{egB\hbar}{4m_e c} \sigma_3$$

$$i\hbar \partial_t \begin{pmatrix} \psi_+(t) \\ \psi_-(t) \end{pmatrix} = \frac{egB\hbar}{4m_e c} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \psi_+(t) \\ \psi_-(t) \end{pmatrix}$$

$\sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$

Ansatz $\begin{pmatrix} \psi_+(t) \\ \psi_-(t) \end{pmatrix} = e^{-i\omega t} \begin{pmatrix} \alpha_+ \\ \alpha_- \end{pmatrix}$ مطروحات ω

$$\cancel{\hbar\omega} e^{-i\omega t} \begin{pmatrix} \alpha_+ \\ \alpha_- \end{pmatrix} = \frac{egB\hbar}{4m_e c} e^{-i\omega t} \begin{pmatrix} \alpha_+ \\ -\alpha_- \end{pmatrix}$$

1) $\omega_1 = + \frac{egB}{4m_e c}$

$\alpha_- = 0 \leftarrow \alpha_- = -\alpha_+$

α_+ برآیند چرخش

$$\begin{pmatrix} \alpha_+ \\ 0 \end{pmatrix}$$

2) $\omega_2 = - \frac{egB}{4m_e c}$

$\alpha_+ = 0 \leftarrow \alpha_+ = -\alpha_-$

α_- برآیند چرخش

$\omega_2 = -\omega_1$

$$\begin{pmatrix} 0 \\ \alpha_- \end{pmatrix}$$

$$|\psi(t)\rangle = \begin{pmatrix} \psi_+(t) \\ \psi_-(t) \end{pmatrix} = e^{-i\omega_1 t} \begin{pmatrix} \alpha_+ \\ 0 \end{pmatrix} + e^{-i\omega_2 t} \begin{pmatrix} 0 \\ \alpha_- \end{pmatrix}$$

$$|\psi(t)\rangle = \begin{pmatrix} e^{-i\omega_1 t} \alpha_+ \\ e^{+i\omega_1 t} \alpha_- \end{pmatrix} \quad \omega_1 = \frac{egB}{4m_e c}$$

فرض: (α_+) و (α_-) در حالت مجله S_x به ازای دفر مقدار $+\frac{\hbar}{2}$

سوال: این حالت چگونه به ازای تمام کول سده اند؟

موضوع: (α_+) و در حالت مجله S_x به ازای درجه مدار $+\frac{\hbar}{2}$

سوال: این حالت چگونه با زمان تحول پیدا می کند؟

پاسخ: $\begin{pmatrix} \alpha_+ \\ \alpha_- \end{pmatrix} = ?$

$$S_x = \frac{\hbar}{2} \sigma_x = \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$S_x \begin{pmatrix} a \\ b \end{pmatrix} = \oplus \frac{\hbar}{2} \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \frac{\hbar}{2} \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\begin{pmatrix} b \\ a \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix} \Rightarrow b = a$$

$$\begin{pmatrix} a \\ a \end{pmatrix} \rightarrow \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \begin{pmatrix} \alpha_+ \\ \alpha_- \end{pmatrix} = \chi_+ \text{ به ازای } S_x \text{ درجه مدار } +\frac{\hbar}{2} \text{ است.}$$

$t=0$

$$\langle S_x \rangle = \langle \chi_+ | S_x | \chi_+ \rangle$$

$$= \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} (1 \ 1) \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$= \frac{\hbar}{2}$$

$t=0$

$$\langle S_y \rangle = \langle \chi_+ | S_y | \chi_+ \rangle$$

$$= \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} (1 \ 1) \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$= 0$$

$$\langle S_z \rangle = \langle \chi_+ | S_z | \chi_+ \rangle$$

$$= \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} (1 \ 1) \frac{\hbar}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$= 0$$

$$\chi_+ \stackrel{t=0}{=} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\chi_+(t) = \frac{1}{\sqrt{2}} \begin{pmatrix} e^{-i\omega t} \\ e^{+i\omega t} \end{pmatrix}$$

$$\langle S_x \rangle = \langle \chi_+(t) | S_x | \chi_+(t) \rangle$$

$$= \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \begin{pmatrix} e^{+i\omega t} & e^{-i\omega t} \end{pmatrix} \frac{\hbar}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} e^{-i\omega t} \\ e^{+i\omega t} \end{pmatrix}$$

$$= \frac{\hbar}{4} \begin{pmatrix} e^{i\omega t} & e^{-i\omega t} \end{pmatrix}_{1 \times 2} \begin{pmatrix} e^{i\omega t} \\ e^{-i\omega t} \end{pmatrix}_{2 \times 1}$$

$$= \frac{\hbar}{4} (e^{2i\omega t} + e^{-2i\omega t})$$

$$= \frac{\hbar}{2} \cos 2\omega t$$

$t=0$

$$\langle S_y \rangle = \langle \chi_+(t) | S_y | \chi_+(t) \rangle$$

$$\begin{aligned}
\langle S_y \rangle &= \langle \chi_+(t) | S_y | \chi_+(t) \rangle \\
&= \frac{1}{\sqrt{2}} \frac{1}{\sqrt{2}} \begin{pmatrix} e^{i\omega_1 t} & e^{-i\omega_1 t} \end{pmatrix} \frac{\hbar}{2} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} e^{-i\omega_1 t} \\ e^{i\omega_1 t} \end{pmatrix} \\
&= \frac{\hbar}{4} \begin{pmatrix} e^{i\omega_1 t} & e^{-i\omega_1 t} \end{pmatrix} \begin{pmatrix} -i e^{i\omega_1 t} \\ i e^{-i\omega_1 t} \end{pmatrix} \\
&= \frac{\hbar}{4} \left(-i e^{2i\omega_1 t} + i e^{-2i\omega_1 t} \right) \\
&= \frac{\hbar}{4} (-i) \left(e^{2i\omega_1 t} - e^{-2i\omega_1 t} \right) \\
&= \frac{\hbar}{4} (-i) (2i \sin 2\omega_1 t) \\
&= \frac{\hbar}{2} \sin 2\omega_1 t \quad t=0
\end{aligned}$$

لا يبرر $\omega_1 = \frac{egB}{4m_e c}$
سكوير دوتين $2\omega_1 = \frac{egB}{2m_e c}$

$$\langle S_z \rangle = 0$$

